

Integrodifference equations in spatial ecology

Lecture 18: Spatial Heterogeneity II

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Small-scale Heterogeneity

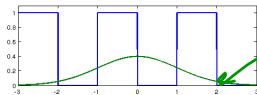
$$N_{L+1}(x) = \int |K(x-y)F(N_L(y), y)| dy$$

$L_1 = \dots$
for persistence

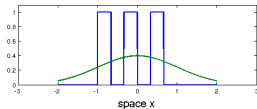


What if landscape heterogeneity is much smaller than dispersal distance?

$C^* = \dots \rightarrow$ Laplace kernel



Dispersal kernel



same %



average?

①

②

Heterogeneous linear IDE model

$$R(y) = \begin{cases} R_1 \\ R_2 \end{cases}$$

↓

$$N_{t+1}(x) = Q[N_t](x) = \int_{-\infty}^{\infty} K(x-y) \underbrace{R(y) N_t(y)} dy$$

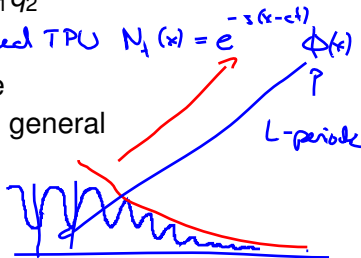
- Special case: Laplace kernel, piecewise constant growth function

$$\cosh(sL) = \cosh(q_1 L_1) \cosh(q_2 L_2) + \frac{q_1^2 + q_2^2}{2q_1 q_2} \sinh(q_1 L_1) \sinh(q_2 L_2),$$

- $q_i = \sqrt{1 - e^{s c} R_i}$

$c = c(s)$ speed TPU $N_1(x) = e^{-s(x-c)}$

- Exact but implicit and specific to Laplace
- Goal today: approximate but explicit and general



The set-up

$$K(x-y; y) = \frac{a}{2} e^{-a|x-y|}$$

$a = a(y)$

$$N_{t+1}(x) = \int_{-\infty}^{\infty} K(x-y; y) R(y) N_t(y) dy,$$

- K depends on distance, but parameter(s) may depend on initial location
- R, K are L -periodic (in second argument)
- Ansatz $N_t(x) = \exp(-s(x - ct))\phi(x)$, where ϕ is L -periodic
- Goal: make parameter L appear in the equation, then let $L \rightarrow 0$.

$$e^{-s(x - c(t+1))} \phi(x) = \int_{-\infty}^{\infty} K(x-y; y) R(y) e^{-s(y - ct)} \phi(y) dy$$

x is L -periodic

$$e^x \phi(x) = \int_{-\infty}^{\infty} K(x-y; y) e^{s(x-y)} R(y) \phi(y) dy$$

$x = L\omega$

The scaling

Apply $x = Lw$, $y = Lz$ to

$$e^{sL} \phi(x) = \int_{-\infty}^{\infty} K(x-y; y) e^{s(x-y)} R(y) \phi(y) dy$$

$$e^{sL} \phi(Lw) = \int_{-\infty}^{\infty} L K(L(w-z); Lz) e^{sL(w-z)} R(Lz) \phi(Lz) dz$$

$$e^{sL} \hat{\phi}(w) = \int_{-\infty}^{\infty} L \hat{K}(L(w-z); z) e^{sL(w-z)} \hat{R}(z) \hat{\phi}(z) dz$$

$\hat{\phi}, \hat{R}, \hat{K}(\cdot, z)$ are 1-periodic

$$e^{sL} \hat{\phi}(w) = \int_0^1 \underbrace{\sum_{n \in \mathbb{Z}} L \hat{K}(L(w-z-n); z) e^{sL(w-z-n)} \hat{R}(z) \hat{\phi}(z)}_{= M(s; z)} dz$$

The sum

$$\sum_{n=-\infty}^{\infty} L \hat{K}(L(w-z-n); z) e^{sL(w-z-n)} \quad \text{as } L \rightarrow 0$$

\downarrow
 x_n

$$\int f(x) dx = \sum_n f(x_n) \cdot \Delta x \quad \Delta x = L$$

$$\text{as } L \rightarrow 0 \quad \text{we get} \quad \int_{-\infty}^{\infty} \hat{K}(w-z; z) e^{s(w-z)} dw = \Pi(s; z)$$

The final step

$$| e^{sc} \hat{\phi}(w) \approx \int_0^1 \hat{R}(z) M(s; z) \hat{\phi}(z) dz$$

\nwarrow \nearrow
 $= \hat{\phi}$ indep. of w indep. of w

$$e^{sc} = \int_0^1 \hat{R}(z) \Pi(s; z) dz = \bar{R} \cdot \Pi(s)$$

\uparrow
if \hat{R}, Π are indep. of z

$$\Rightarrow c = \frac{1}{s} \ln \left(\int_0^1 \hat{R}(z) \Pi(s; z) dz \right)$$

\uparrow
if $\Pi(s)$ \bar{R}

$$= \frac{1}{s} \ln \left(\int_0^1 \hat{R}(z) dz \cdot \Pi(s) \right)$$

Illustrations

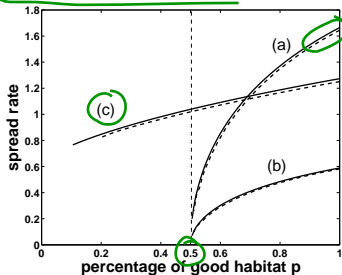
$$N_{\text{env}}(x) = \int_{-\infty}^{\infty} K(x-y, y) R(y) N_{\text{e}}(y) dy$$

Scaled $L=1$ choose variance

large variance \leftrightarrow small L

$$R = \begin{cases} R_1 > 1 \\ R_2 = 0 \end{cases} \quad \frac{L_1}{L} = p$$

Gaussian kernel



(a) $R_2 = 0$, small period, large variance

(b) $R_2 = 0$, large period, small variance

(c) $R_1 = R_2$, mixed variance

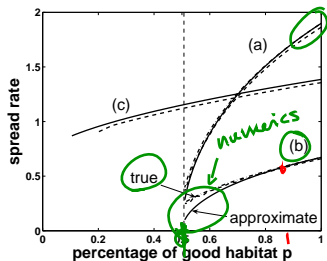
$L \rightarrow 0$

large L

Dewhurst & L 2009

Illustrations

Laplace kernel

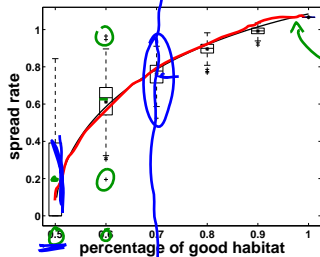


- (a) $R_2 = 0$, small period, large variance
- (b) $R_2 = 0$, large period, small variance
- (c) $R_1 = R_2$, mixed variance

Illustrations

Random Landscape

generated with percentage ↑



approx

- 0) Choose p
- 1) Generate landscape
- 2) Initialize N_0
- 3) Run, find c
- 4) Repeat 100 times

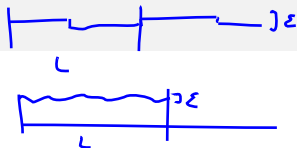
$c_1 \dots c_{100}$

$$\lim_{t \rightarrow \infty} x_t - x_{t-1}$$



- Gaussian kernels
- 100 landscapes each
- mean, median, percentile, outliers

Small variation

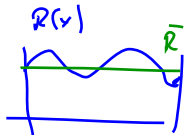


Start again with

$$N_{t+1}(x) = \int K(x-y)R(y)N_t(y)dy$$

and assume

$$R(x) = \bar{R}(1 + \epsilon R_1 + O(\epsilon^2))$$



where

$$\bar{R} = \frac{1}{L} \int_0^L R(x) dx, \quad \int_0^L R_1(x) dx = 0.$$

$$N_{t+1}(x) = \underbrace{\int K(x-y) \bar{R} N_t(y) dy}_{\mathcal{K}_0[N_t]} + \epsilon \underbrace{\int K(x-y) \bar{R} R_1(y) N_t(y) dy}_{\mathcal{K}_1[N_t]} + O(\epsilon^2)$$

Expansion in ϵ

$$N_\epsilon(x) = e^{-s(x-\epsilon t)} \phi(x) \Rightarrow e^{s\epsilon} \phi(x) = \overbrace{(\mathcal{K}_0 + \epsilon \mathcal{K}_1)} [\phi] + O(\epsilon^2)$$

$$\underline{c(s, \epsilon) = c_0(s) + \epsilon c_1(s) + O(\epsilon^2)} \quad \phi(x, \epsilon) = \phi_0(x) + \epsilon \phi_1(x) + O(\epsilon^2)$$

$$\Rightarrow e^{s\epsilon} = e^{s(c_0 + \epsilon c_1 + \dots)} = e^{s c_0} + \epsilon c_1 e^{s c_0} + \epsilon^2 \dots$$

$$(e^{s c_0} + \epsilon c_1 e^{s c_0}) (\phi_0 + \epsilon \phi_1) = \mathcal{K}_0 \phi_0 + \epsilon (\mathcal{K}_1 \phi_0 + \mathcal{K}_0 \phi_1) + \epsilon^2 \dots$$



$$\mathcal{K}_0[\phi] = \int k(x-y) e^{s(x-y)} \bar{R} \phi dy$$

$$\mathcal{K}_1[\phi] = \int k(x-y) e^{s(x-y)} \bar{R} R_1(y) \phi dy$$

The lowest terms

$$(e^{s c_0} + \epsilon c_1 e^{s c_0})(\phi_0 + \epsilon \phi_1) = \mathcal{K}_0 \phi_0 + \epsilon(\mathcal{K}_0 \phi_1 + \mathcal{K}_1 \phi_0)$$

$$\Sigma^0: \quad \underline{e^{s c_0} \phi_0 = \mathcal{K}_0 \phi_0} = \int \underbrace{\kappa(x-y)}_{e^{s(x-y)}} \bar{\mathcal{R}} \phi_0(y) dy \quad \left. \begin{array}{l} \phi_0(y) = \text{const} \\ \mathcal{M}(s) \cdot \bar{\mathcal{R}} \end{array} \right\}$$

$$\Rightarrow c_0 = \frac{1}{s} \ln(\mathcal{M}(s) \bar{\mathcal{R}})$$

$$\Sigma^1: \quad e^{s c_0} c_1 \phi_0 + e^{s c_0} \phi_1 = \mathcal{K}_0 \phi_1 + \mathcal{K}_1 \phi_0$$

$$\underline{e^{s c_0} c_1 \phi_0 - \mathcal{K}_1 \phi_0} = \underline{-e^{s c_0} \phi_1 + \mathcal{K}_0 \phi_1}$$

Claim: $c_1 = 0$

L -periodic functions $\mathcal{L}^2[0, L]$ with $\langle \cdot, \cdot \rangle$

$$e^{s_0} \phi_0 - \mathcal{K}_0 \phi_0 = 0$$

$$\begin{aligned} & \langle \phi_0^*, e^{s_0} \phi_0 - \mathcal{K}_0 \phi_0 \rangle \\ &= \langle \underbrace{e^{s_0} \phi_0^* - \mathcal{K}_0^* \phi_0^*}_{=0}, \phi_0 \rangle = 0 \end{aligned}$$

$$= \langle \phi_0^*, e^{s_0} c_1 \phi_0 - \mathcal{K}_1 \phi_0 \rangle = 0$$

$$\Rightarrow \langle \phi_0^*, e^{s_0} c_1 \phi_0 \rangle - \langle \phi_0^*, \mathcal{K}_1 \phi_0 \rangle = 0$$

$$\Leftrightarrow c_1 = \frac{\langle \phi_0^*, \mathcal{K}_1 \phi_0 \rangle}{\langle \phi_0^*, e^{s_0} \phi_0 \rangle} \stackrel{!}{=} 0$$

$$\begin{aligned} & \int_0^L \phi_0^*(x) \int_0^L k(x-y) \bar{r}(y) \phi_0(y) dy dx \\ &= \phi_0^* \bar{r} \int_0^L \int_0^L k(x-y) r(y) dy dx \\ &= \phi_0^* \bar{r} \int_0^L \int_0^L k(\omega) r(y) dy d\omega \\ &= \phi_0^* \bar{r} \int_0^L k(\omega) \left[\int_0^L r(y) dy \right] d\omega \\ & \quad \quad \quad = 0 \end{aligned}$$

Summary

- Averaging over fine-grained landscapes
- Averaging over small variation
- $c(s, \epsilon) = c_0(s) + O(\epsilon^2)$